

Long time behavior of Mean Field Games

P. Cardaliaguet

(Paris-Dauphine)

Joint work (in progress) with A. Porretta (Roma Tor Vergata)

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The MFG system

Given a finite horizon $T > 0$, we consider the MFG system

$$(MFG) \quad \begin{cases} -\partial_t u^T - \sigma \Delta u^T + H(x, Du^T) = f(x, m^T(t)) & \text{in } (0, T) \times \mathbb{T}^d \\ \partial_t m^T - \sigma \Delta m^T - \operatorname{div}(m^T D_p H(x, Du^T)) = 0 & \text{in } (0, T) \times \mathbb{T}^d \\ u^T(T, x) = g(x, m^T(T)), m^T(0, \cdot) = m_0 & \text{in } \mathbb{T}^d \end{cases}$$

where

- $u = u(t, x)$ and $m = m(t, x)$ are the unknown,
- $\sigma \geq 0$ is the viscosity,
- $H = H(x, p) : \mathbb{T}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ is a smooth, unif. convex in p , Hamiltonian,
- $f, g : \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d) \rightarrow \mathbb{R}$ are “smooth”,
($\mathcal{P}(\mathbb{T}^d)$ = the set of Borel probability measures on \mathbb{T}^d)
- $m_0 \in \mathcal{P}(\mathbb{T}^d)$ is a smooth positive density

The MFG system has been introduced by Lasry-Lions and Huang-Caines-Malhamé to study optimal control problems with infinitely many controllers.

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The limit problem

Let (u^T, m^T) be the solution to

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Study the limit as $T \rightarrow +\infty$ of the pair (u^T, m^T) .

- **Motivation** : one numerically observes that the pair (u^T, m^T) quickly stabilizes as T is large (when f and g are monotone).
- In contrast with similar problem for HJ equation, **initial** and **terminal** conditions for the system.

The limit problem

One expects that (u^T, m^T) “converges” to the solution of the **ergodic MFG problem**

$$(MFG - erg) \quad \begin{cases} \bar{\lambda} - \sigma \Delta \bar{u} + H(x, D\bar{u}) = f(x, \bar{m}) & \text{in } \mathbb{T}^d \\ -\sigma \Delta \bar{m} - \operatorname{div}(\bar{m} D_p H(x, D\bar{u})) = 0 & \text{in } \mathbb{T}^d \\ \bar{m} \geq 0 \text{ in } \mathbb{T}^d, \quad \int_{\mathbb{T}^d} \bar{m} = 1 \end{cases}$$

where now the unknown are $\bar{\lambda}$, $\bar{u} = \bar{u}(x)$ and $\bar{m} = \bar{m}(x)$.

- For the Fokker-Plank equation driven by a vector-field V :

$$\partial_t m^T - \sigma \Delta m^T - \operatorname{div}(m^T V(x)) = 0 \quad \text{in } (0, T) \times \mathbb{T}^d$$

(exponential) convergence of m^T to the ergodic measure is well-known.

- For HJ equations :

$$\partial_t u - \sigma \Delta u + H(x, Du) = f(x) \quad \text{in } (0, +\infty) \times \mathbb{T}^d$$

- Ergodic constant $\bar{\lambda}$, convergence of $u(T, \cdot)/T$: Lions-Papanicolau-Varadhan, ...
- Convergence of $u(T, \cdot) - \bar{\lambda}T$: Fathi, Roquejoffre, Fathi-Siconolfi, Barles-Souganidis, ...

- For the MFG system, convergence of u^T/T and m^T :

- Lions (Cours in Collège de France)
- Gomes-Mohr-Souza (discrete setting)
- C.-Lasry-Lions-Porretta (viscous setting), C. (Hamilton-Jacobi)
- Turnpike property (Samuelson, Porretta-Zuazua, Trélat,...)

- Long-time behavior not known so far.

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1 The long time average

2 The master equation

3 The long-time behavior

Outline

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Standing assumptions

- $H : \mathbb{T}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ is smooth, with :

$$C^{-1}I_d \leq D_{pp}^2 H(x, p) \leq CI_d \text{ and } D_x H(x, p) \cdot p \geq -C|p|^2 \quad \text{for } (x, p) \in \mathbb{T}^d \times \mathbb{R}^d.$$

- the maps $f, g : \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d) \rightarrow \mathbb{R}$ are **monotone** : for any $m, m' \in \mathcal{P}(\mathbb{T}^d)$,

$$\int_{\mathbb{T}^d} (f(x, m) - f(x, m')) d(m - m')(x) \geq 0, \quad \int_{\mathbb{T}^d} (g(x, m) - g(x, m')) d(m - m')(x) \geq 0$$

- the maps f, g are Lipschitz continuous and $f(\cdot, m), g(\cdot, m)$ are uniformly bounded in $C^{2+\alpha}$ for some $\alpha \in (0, 1)$.

Example. If f is of the form :

$$f(x, m) = \int_{\mathbb{R}^d} \Phi(z, (\rho \star m)(z)) \rho(x - z) dz,$$

where

- \star denotes the usual convolution product (in \mathbb{R}^d),
- $\Phi = \Phi(x, r) : \mathbb{T}^d \times [0, +\infty) \rightarrow \mathbb{R}$ is a smooth map, nondecreasing w.r. to r ,
- ρ is a smooth, even function with compact support.

Then f satisfies our conditions.

Indeed, for any $m, m' \in \mathcal{P}(\mathbb{T}^d)$,

$$\begin{aligned} & \int_{\mathbb{T}^d} (f(x, m) - f(x, m')) d(m - m')(x) \\ &= \int_{\mathbb{T}^d} [\Phi(y, \rho \star m(y)) - \Phi(y, \rho \star m'(y))] (\rho \star m(y) - \rho \star m'(y)) dy \geq 0, \end{aligned}$$

since ρ is even and Φ is nondecreasing with respect to the second variable. So f is monotone.

Basic convergence result

Let U^T, M^T be the **scaled functions** on $\mathbb{T}^d \times [0, 1]$:

$$U^T(t, x) := u^T(tT, x) \quad ; \quad M^T(t, x) := m^T(tT, x)$$

Theorem (C.-Lasry-Lions-Porretta, '13)

As $T \rightarrow +\infty$,

- $\frac{U^T(t, \cdot)}{T}$ converges uniformly to $-(1-t)\bar{\lambda}$ in $\mathbb{T}^d \times [0, 1]$.
- $M^T(t)$ converges to \bar{m} in $L^2(\mathbb{T}^d)$, uniformly on compact intervals of $(0, 1)$.

Actually, convergence with an exponential rate.

Ingredients of proof

Lemma

The map u^T is **uniformly semi-concave in space**.

In particular, u^T is uniformly Lipschitz continuous in space.

Proof : Comes from the regularity of $f(\cdot, m^T)$ and the fact that $H = H(x, p)$ is uniformly convex in p .

Main energy inequality. Computing $\frac{d}{dt} \int_{\mathbb{T}^d} u^T(t, x) m^T(t, x) dx$ and integrating we get the **main energy inequality** :

$$\begin{aligned} & \int_0^T \int_{\mathbb{T}^d} C^{-1}(m^T + \bar{m}) |Du^T - D\bar{u}|^2 + (f(x, m^T) - f(x, \bar{m}))(m^T - \bar{m}) dx dt \\ & \leq - \left[\int_{\mathbb{T}^d} (u^T - \bar{u})(m^T - \bar{m}) dx \right]_0^T \end{aligned}$$

where the RHS is bounded because

- at $t = T$, $\left| \int_{\mathbb{T}^d} (u^T(T, x) - \bar{u}(x))(m^T(T, x) - \bar{m}(x)) dx \right| \leq 2(\|g\|_\infty + \|\bar{u}\|_\infty)$
- at $t = 0$, $\left| \int_{\mathbb{T}^d} (u^T(0, x) - \bar{u}(x))(m^T(0, x) - \bar{m}(x)) dx \right|$

$$\leq \left| \int_{\mathbb{T}^d} (u^T(0, x) - \int_{\mathbb{T}^d} u^T(0)) (m^T(0, x) - \bar{m}(x)) dx \right| + 2\|\bar{m}\|_\infty$$

$$\leq CLip(u^T(0, \cdot)) + 2\|\bar{m}\|_\infty$$

So

$$\int_0^T \int_{\mathbb{T}^d} \frac{(m^T + \bar{m})}{2} |Du^T - D\bar{u}|^2 + (f(x, m^T) - f(x, \bar{m}))(m^T - \bar{m}) \, dxdt \leq C$$

where $\bar{m} > 0$.

In particular

$$\lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T \int_{\mathbb{T}^d} |Du^T - D\bar{u}|^2 \, dxdt = 0 ,$$

which is equivalent to

$$\lim_{T \rightarrow +\infty} \int_0^1 \int_{\mathbb{T}^d} |DU^T - D\bar{u}|^2 \, dxdt = 0 ,$$

This implies

- the convergence of m^T ,
- and then the convergence of u^T/T .

Outline

1 The long time average

2 The master equation

3 The long-time behavior

The master equation

In order to study the long time behavior of the solution (u^T, m^T) , we use the [master equation](#), which subsumes the MFG system into a single equation :

$$\left\{ \begin{array}{l} -\partial_t U - \Delta_x U + H(x, D_x U) - f(x, m) \\ \quad - \int_{\mathbb{T}^d} \operatorname{div}_y [D_m U] \, dm(y) + \int_{\mathbb{T}^d} D_m U \cdot D_p H(y, D_x U) \, dm(y) = 0 \\ \quad \quad \quad \text{in } [0, T] \times \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d) \\ U(T, x, m) = G(x, m) \quad \text{in } \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d) \end{array} \right.$$

where $U = U(t, x, m) : [0, T] \times \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d) \rightarrow \mathbb{R}$.

Derivatives in the space of measures

We denote by $\mathcal{P}(\mathbb{T}^d)$ the set of Borel probability measures on \mathbb{T}^d , endowed for the Monge-Kantorovich distance

$$\mathbf{d}_1(m, m') = \sup_{\phi} \int_{\mathbb{T}^d} \phi(y) d(m - m')(y),$$

where the supremum is taken over all Lipschitz continuous maps $\phi : \mathbb{T}^d \rightarrow \mathbb{R}$ with a Lipschitz constant bounded by 1.

Given $U : \mathcal{P}(\mathbb{T}^d) \rightarrow \mathbb{R}$, we consider 2 notions of derivatives :

- The directional derivative $\frac{\delta U}{\delta m}(m, y)$
(see, e.g., Mischler-Mouhot)
- The intrinsic derivative $D_m U(m, y)$
(see, e.g., Otto, Ambrosio-Gigli-Savaré, Lions)

Directional derivative

A map $U : \mathcal{P}(\mathbb{T}^d) \rightarrow \mathbb{R}$ is \mathcal{C}^1 if there exists a continuous map $\frac{\delta U}{\delta m} : \mathcal{P}(\mathbb{T}^d) \times \mathbb{T}^d \rightarrow \mathbb{R}$ such that, for any $m, m' \in \mathcal{P}(\mathbb{T}^d)$,

$$U(m') - U(m) = \int_0^1 \int_{\mathbb{T}^d} \frac{\delta U}{\delta m}((1-s)m + sm', y) d(m' - m)(y) ds.$$

Note that $\frac{\delta U}{\delta m}$ is defined up to an additive constant. We adopt the normalization convention

$$\int_{\mathbb{T}^d} \frac{\delta U}{\delta m}(m, y) dm(y) = 0.$$

Intrinsic derivative

If $\frac{\delta U}{\delta m}$ is of class \mathcal{C}^1 with respect to the second variable, **the intrinsic derivative** $D_m U : \mathcal{P}(\mathbb{T}^d) \times \mathbb{T}^d \rightarrow \mathbb{R}^d$ is defined by

$$D_m U(m, y) := D_y \frac{\delta U}{\delta m}(m, y)$$

For instance, if $U(m) = \int_{\mathbb{T}^d} g(x) dm(x)$, then $\frac{\delta U}{\delta m}(m, y) = g(y) - \int_{\mathbb{T}^d} g dm$ while $D_m U(m, y) = Dg(y)$.

Remarks.

- The directional derivative is fruitful for computations.
- The intrinsic derivative encodes the variation of the map in $\mathcal{P}(\mathbb{T}^d)$. For instance :

$$\|D_m U\|_\infty = \text{Lip } U$$

Strengthened assumptions

- $H : \mathbb{T}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ is smooth, with :

$$C^{-1} I_d \leq D_{pp}^2 H(x, p) \leq C I_d \text{ and } D_x H(x, p) \cdot p \geq -C|p|^2 \quad \text{for } (x, p) \in \mathbb{T}^d \times \mathbb{R}^d.$$

- the maps $f, g : \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d) \rightarrow \mathbb{R}$ are **monotone** : for any $m, m' \in \mathcal{P}(\mathbb{T}^d)$,

$$\int_{\mathbb{T}^d} (f(x, m) - f(x, m')) d(m - m')(x) \geq 0, \quad \int_{\mathbb{T}^d} (g(x, m) - g(x, m')) d(m - m')(x) \geq 0$$

- the maps f, g are C^1 : there exists $\alpha \in (0, 1)$ such that

$$\sup_{m \in \mathcal{P}(\mathbb{T}^d)} \left(\|f(\cdot, m)\|_{2+\alpha} + \left\| \frac{\delta f(\cdot, m, \cdot)}{\delta m} \right\|_{(2+\alpha, 2+\alpha)} \right) + \text{Lip}\left(\frac{\delta f}{\delta m}\right) < \infty.$$

and the same for g .

- The derivatives of the maps f, g are **symmetric** :

$$\frac{\delta f}{\delta m}(x, m, y) = \frac{\delta f}{\delta m}(y, m, x) \text{ and } \frac{\delta g}{\delta m}(x, m, y) = \frac{\delta g}{\delta m}(y, m, x)$$

The master equation

It is the backward equation

$$\begin{aligned}
 \text{(M)} \quad & \left\{ \begin{aligned}
 & -\partial_t U(t, x, m) - \Delta_x U(t, x, m) + H(x, D_x U(t, x, m)) - f(x, m) \\
 & - \int_{\mathbb{T}^d} \operatorname{div}_y [D_m U](t, x, m, y) dm(y) \\
 & + \int_{\mathbb{T}^d} D_m U(t, x, m, y) \cdot D_p H(y, D_x U(t, y, m)) dm(y) = 0 \\
 & \qquad \qquad \qquad \text{for } (t, x, m) \in [0, T] \times \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d), \\
 & U(T, x, m) = G(x, m), \quad \text{for } (x, m) \in \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d)
 \end{aligned} \right.
 \end{aligned}$$

Theorem (C.-Delarue-Lasry-Lions, 2015)

Under our assumptions, the master equation **(M)** has a unique classical solution.

In fact, holds for the master equation [with common noise](#).

Advantage of the master equation

- The solution is smooth, defined for all times and subsumes the MFG system.
- As noticed by Lions, the MFG system forms the characteristics of the master equation : given $(t_0, m_0) \in \mathcal{P}(\mathbb{T}^d)$, let $(m(t))$ solve the McKean-Vlasov equation :

$$\begin{cases} \partial_t m - \Delta m - \operatorname{div}(m D_p H(x, DU(t, x, m))) = 0 & \text{in } (t_0, T) \times \mathbb{T}^d \\ m(t_0) = m_0 & \text{in } \mathbb{T}^d \end{cases}$$

and set $u(t, x) = U(t, x, m(t))$.

Then (u, m) is the solution of the MFG system starting from m_0 at time t_0 .

- Conversely, given an initial position $(t_0, m_0) \in (0, T) \times \mathcal{P}(\mathbb{T}^d)$ and (u, m) a solution of the MFG system starting from m_0 at time t_0 , the map U defined by

$$U(t_0, x, m_0) := u(t_0, x)$$

solve the master equation.

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The master cell-problem

Theorem (C.-Porretta, 2016)

There is a unique constant λ such that the [master cell-problem](#) :

$$\lambda - \Delta_x \chi(x, m) + H(x, D_x \chi(x, m)) - \int_{\mathbb{T}^d} \operatorname{div}(D_m \chi(x, m)) dm \\ + \int_{\mathbb{T}^d} D_m \chi(x, m) \cdot H_p(x, D_x \chi(x, m)) dm = f(x, m) \quad \text{in } \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d)$$

has a (weak) solution.

Moreover, if $(\bar{\lambda}, \bar{u}, \bar{m})$ is the solution to the [ergodic MFG system](#) :

$$\begin{cases} \bar{\lambda} - \Delta \bar{u} + H(x, D\bar{u}) = f(x, \bar{m}) & \text{in } \mathbb{T}^d \\ -\Delta \bar{m} - \operatorname{div}(\bar{m} D_p H(x, D\bar{u})) = 0 & \text{in } \mathbb{T}^d \\ \bar{m} \geq 0 \text{ in } \mathbb{T}^d, \quad \int_{\mathbb{T}^d} \bar{m} = 1 \end{cases}$$

then

$$\bar{\lambda} = \lambda \quad \text{and} \quad D_x \chi(x, \bar{m}) = D\bar{u}(x) \quad \forall x \in \mathbb{T}^d.$$

The construction of χ relies as usual on a discounted equation :

$$\delta U^\delta - \Delta_x U^\delta + H(x, D_x U^\delta) - \int_{\mathbb{T}^d} \operatorname{div}(D_m U^\delta) dm \\ + \int_{\mathbb{T}^d} D_m U^\delta \cdot H_p(x, D_x U^\delta(x, m)) dm = f(x, m) \text{ in } \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d).$$

The main step is the proof of the Lipschitz estimate :

Proposition

There is a constant C , depending on the data only, such that

$$\|D_m U^\delta(\cdot, m, \cdot)\|_{2+\alpha, 1+\alpha} \leq C.$$

In particular, $U^\delta(\cdot, \cdot)$ is uniformly Lipschitz continuous.

Difficulty : equation for U^δ neither coercive nor elliptic in m .

Idea of proof

Representation formulas. Fix $m_0 \in \mathcal{P}(\mathbb{T}^d)$ a initial condition and (u^δ, m^δ) the associated solution of the discounted MFG system :

$$\begin{cases} -\partial_t u^\delta + \delta u^\delta - \Delta u^\delta + H(x, Du^\delta) = f(x, m^\delta(t)) & \text{in } (0, +\infty) \times \mathbb{T}^d \\ \partial_t m^\delta - \Delta m^\delta - \operatorname{div}(m^\delta H_p(x, Du^\delta)) = 0 & \text{in } (0, +\infty) \times \mathbb{T}^d \\ m^\delta(0, \cdot) = m_0 \text{ in } \times \mathbb{T}^d, \quad u^\delta \text{ bounded.} \end{cases}$$

For any smooth map μ_0 with $\int_{\mathbb{T}^d} m_0 = 0$, one can show that

$$\int_{\mathbb{T}^d} \frac{\delta U^\delta}{\delta m}(x, m_0, y) \mu_0(y) dy = w(0, x),$$

where (w, μ) is the unique solution to the linearized system

$$\begin{cases} -\partial_t w + \delta w - \Delta w + H_p(x, Du^\delta) \cdot Dw = \frac{\delta f}{\delta m}(x, m^\delta(t))(\mu(t)) & \text{in } (0, +\infty) \times \mathbb{T}^d \\ \partial_t \mu - \Delta \mu - \operatorname{div}(\mu H_p(x, Du^\delta)) - \operatorname{div}(m^\delta H_{pp}(x, Du^\delta) Dw) = 0 & \text{in } (0, +\infty) \times \mathbb{T}^d \\ \mu(0, \cdot) = \mu_0 \text{ in } \mathbb{T}^d, \quad w \text{ bounded.} \end{cases}$$

The standard energy estimate gives

$$\int_0^\infty e^{-\delta t} m^\delta |Dw|^2 \leq C \int_{\mathbb{T}^d} w(0) \mu_0.$$

Estimate of μ . Recall that μ solves

$$\begin{cases} \partial_t \mu - \Delta \mu - \operatorname{div}(\mu H_p(x, Du^\delta)) - \operatorname{div}(m^\delta H_{pp}(x, Du^\delta) Dw) = 0 & \text{in } (0, +\infty) \times \mathbb{T}^d \\ \mu(0, \cdot) = \mu_0 & \text{in } \mathbb{T}^d. \end{cases}$$

Following [CLLP], there exists $\omega > 0$, depending on $\|D_p H\|_\infty$ only, such that, for $t \geq 0$,

$$\|\mu(t)\|_1 \leq C \left(\|\mu_0\|_{(C^{2+\alpha})'} e^{-\omega t} + \left(\int_0^t \int_{\mathbb{T}^d} |m^\delta D_{pp}^2 H(x, Du^\delta) Dw|^2 \right)^{\frac{1}{2}} \right).$$

Using the energy estimate then yields to

$$\|\mu(t)\|_1 \leq C \left(\|\mu_0\|_{(C^{2+\alpha})'} e^{-\omega t} + e^{\delta t/2} \left(\int_{\mathbb{T}^d} w(0) \mu_0 \right)^{\frac{1}{2}} \right).$$

Estimate of w . Next we apply estimates in [CLLP] to $w = w(t, x)$, which satisfies

$$-\partial_t w + \delta w - \Delta w + H_p(x, Du^\delta).Dw = \int_{\mathbb{T}^d} \frac{\delta f}{\delta m}(x, m^\delta(t), y) \mu(t, y) dy \quad \text{in } (0, +\infty) \times \mathbb{T}^d.$$

We obtain :

$$\|w(t) - \langle w(t) \rangle\|_\infty \leq C e^{\delta t} \int_t^\infty e^{-\omega(s-t) - \delta s} \|\mu(s)\|_{(C^{2+\alpha})'} ds.$$

Using the estimate for μ , we get therefore :

$$\|w(t) - \langle w(t) \rangle\|_\infty \leq C e^{\delta t} \left(\|\mu(0)\|_{(C^{2+\alpha})'} + \left(\int_{\mathbb{T}^d} w(0) \mu(0) \right)^{\frac{1}{2}} \right).$$

Key step : estimate of $\langle w(t) \rangle$. We first claim that $\xi(t) := \int_{\mathbb{T}^d} w(t, x) m^\delta(t, x) dx = 0$ for $t \geq 0$.
Indeed

$$\frac{d}{dt} \xi(t) + \delta \xi(t) = \int_{\mathbb{T}^d} \int_{\mathbb{T}^d} \frac{\delta f}{\delta m}(x, m^\delta(t), y) \mu(t, y) m^\delta(t, x) dy dx,$$

where, as $\frac{\delta f}{\delta m}(\cdot, m, \cdot)$ is symmetric, the RHS equals

$$\int_{\mathbb{T}^d} \left(\int_{\mathbb{T}^d} \frac{\delta f}{\delta m}(y, m^\delta(t), x) m^\delta(t, x) dx \right) \mu(t, y) dy = 0$$

by convention on the derivative. This easily yields the claim :

$$\int_{\mathbb{T}^d} w(t, x) m^\delta(t, x) dx = 0 \quad \forall t \geq 0.$$

Conclusion. Using the previous estimates we find :

$$\|w(0)\|_{C^{2+\alpha}} \leq C \left(\|\mu_0\|_{(C^{2+\alpha})'} + \left(\int_{\mathbb{T}^d} w(0) \mu_0 \right)^{\frac{1}{2}} \right)$$

Whence

$$\|w(0)\|_{C^{2+\alpha}} = \left\| \int_{\mathbb{T}^d} \frac{\delta U^\delta}{\delta m}(\cdot, m_0, y) \mu_0(y) dy \right\|_{C^{2+\alpha}} \leq C \|\mu_0\|_{(C^{2+\alpha})'}.$$

Main convergence results

Let χ be a solution to the master cell problem. We consider the solution to the backward master equation

$$\begin{cases} -\partial_t U(t, x, m) - \Delta_x U(t, x, m) + H(x, D_x U(t, x, m)) - \int_{\mathbb{T}^d} \operatorname{div}(D_m U(t, x, m)) dm \\ \quad + \int_{\mathbb{T}^d} D_m U(t, x, m) \cdot H_p(t, x, m) dm = f(x, m) & \text{in } (-\infty, 0) \times \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d), \\ U(0, x, m) = G(x, m) & \text{in } \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d) \end{cases}$$

Theorem (C.-Porretta, 2016)

There exists a constant $c \in \mathbb{R}$ such that

$$\lim_{t \rightarrow -\infty} U(t, x, m) + \bar{\lambda}t = \chi(x) + c,$$

uniformly with respect to $(x, m) \in \mathbb{T}^d \times \mathcal{P}(\mathbb{T}^d)$.

The Theorem implies in particular the convergence of the solution to the MFG system as $T \rightarrow +\infty$.

Corollary

Let c be the constant given in the Theorem. For $T > 0$ and $m_0 \in \mathcal{P}(\mathbb{T}^d)$, let (u^T, m^T) be the solution to the MFG system :

$$\begin{cases} -\partial_t u^T - \sigma \Delta u^T + H(x, Du^T) = f(x, m^T(t)) & \text{in } (0, T) \times \mathbb{T}^d \\ \partial_t m^T - \sigma \Delta m^T - \operatorname{div}(m^T D_p H(x, Du^T)) = 0 & \text{in } (0, T) \times \mathbb{T}^d \\ u^T(T, x) = g(x, m^T(T)), m^T(0, \cdot) = m_0 & \text{in } \mathbb{T}^d \end{cases}$$

Then

$$\lim_{T \rightarrow +\infty} u^T(0, x) + \bar{\lambda} T = \chi(x) + c$$

Proof. Indeed, $u^T(0, x) = U(-T, x, m_0)$. The result follows immediately.

Conclusion

We have established the long time behavior of the solution of the MFG system and of the master equation.

Open problems :

- Analysis in more realistic setting (with boundary conditions, non constant diffusion matrices,...)
- Convergence of the discounted MFG system and of the discounted master equation.
- Convergence without the symmetry condition or in the non-monotone setting.

Thank you !