

# Homogenization of a 1D pursuit law with delay

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# Traffic flow modelling: microscopic scale

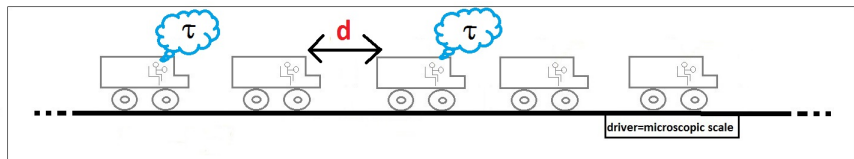


Figure : View of the microscopic scale considered in our study.

# Traffic flow modelling: macroscopic scale



(source: Sytadin.fr)

Figure : Schematic view of the global traffic flow around Paris from sytadin.fr.

# Homogenization process: micro-macro passage



Figure : Schematic description of the homogenization process.

Huge reaction times  $\Rightarrow$  accordion effect (see video)

# Pursuit law

Microscopic dynamics (DDE):

$$\frac{dX_i}{dt}(t) = F(X_{i+1}(t - \tau) - X_i(t - \tau)) \quad (i, t) \in \mathbb{Z} \times (0, +\infty)$$

with initial condition:

$$X_i(t) = x_i^0(t) \quad t \in [-2\tau, 0]$$

## Rescaled equation and expected limit

Hyperbolic rescaling:

$$u^\varepsilon(x, t) := \varepsilon X_{\lfloor \frac{x}{\varepsilon} \rfloor} \left( \frac{t}{\varepsilon} \right)$$

Microscopic model embedded into:

$$\begin{cases} \partial_t u^\varepsilon(x, t) = F \left( \frac{u^\varepsilon(x+\varepsilon, t-\varepsilon\tau) - u^\varepsilon(x, t-\varepsilon\tau)}{\varepsilon} \right) & (x, t) \in \mathbb{R} \times (0, +\infty) \\ u^\varepsilon(x, s) = u_0(x, s) & (x, s) \in \mathbb{R} \times [-2\varepsilon\tau, 0] \end{cases}$$

Expected macroscopic model for vanishing  $\varepsilon$ :

$$\begin{cases} \partial_t u^0(x, t) = F(\partial_x u^0(x, t)) & (x, t) \in \mathbb{R} \times (0, +\infty) \\ u^0(x, 0) = u_0(x, 0) & x \in \mathbb{R} \end{cases}$$

# Outline

- 1 Introduction
- 2 Convergence theorem
- 3 Strict comparison principle
- 4 Convergence proof

# Some references

## Microscopic traffic flow models

[Chandler, Hermann, Montroll; (1958)]

[Gipps; (1981)]

[Costeseque; (2014)]

## Macroscopic traffic flow models

[Lighthill, Whitham; (1955)]

[Richards; (1956)]

## Periodic homogenization for system of ODEs

[Forcadel, Imbert, Monneau; (2007)]

[Forcadel, Imbert, Monneau; (2008)]

## Homogenization with a junction condition

[Forcadel, Salazar; (2014)]

## Homogenization of second order models

[Forcadel, Salazar; (2015)]



# Existence and Uniqueness of solutions

## Assumptions

(B0)

$$F \text{ is: } \begin{cases} \text{non-decreasing} \\ \text{bounded} \\ C_F - \text{Lipschitz} \end{cases}$$

(B1)  $u_0$  is  $L$ -Lipschitz

- Microscopic model ( $\varepsilon$ -singular DDE): Incremental construction
- Macroscopic model (HJ equation): Perron method and comparison principle

# Convergence theorem

## Theorem [F-Monneau]

For  $\tau \in \left(0; \frac{1}{eC_F}\right)$  and under assumptions (B0)-(B1),  $u^\varepsilon$  converges locally uniformly towards  $u^0$ .

The proof relies on a strict comparison principle stated on:

$$\begin{cases} \partial_t u(x, t) = F(u(x+1, t-\tau) - u(x, t-\tau)) & (x, t) \in \mathbb{R} \times (0, +\infty) \\ u(x, s) = u_0(x, s) & (x, s) \in \mathbb{R} \times [-2\tau; 0] \end{cases}$$

# Strict comparison principle

## Theorem [F-Monneau]

Under (B0)-(B1), let  $v$  be a supersolution and  $u$  a subsolution. If:

$$0 < \delta \leq (v-u)(x, t-\tau') \leq \rho(\tau')(v-u)(x, t) \quad \tau' \in [0, \tau], (x, t) \in \mathbb{R} \times [-\tau, 0]$$

where  $\rho$  is non decreasing and such that:

$$1 + C_F \rho(\tau) \int_0^{\tau'} \rho(s) ds < \rho(\tau') \quad \tau' \in [0, \tau]$$

Then we have:

$$0 < \delta e^{-C_F \rho(\tau)t} \leq v(x, t) - u(x, t) \quad (x, t) \in \mathbb{R} \times [0, +\infty)$$

## Restriction on $\tau$

### Lemma

There exist non decreasing  $\rho$  such that:

$$1 + C_F \rho(\tau) \int_0^{\tau'} \rho(s) ds < \rho(\tau') \quad \tau' \in [0, \tau]$$

if and only if  $\tau < \frac{1}{eC_F}$ .

The proof uses comparison principles on affine differential inequalities.

The restriction on  $\tau$  is not sufficient for the strict comparison principle to hold. Vehicles must be suitably spaced out.

# Proof of strict comparison principle (sketch)

We want to prove that:

$$0 < \delta e^{-C_F \rho(\tau)t} \leq d(x, t) := v(x, t) - u(x, t) \quad (x, t) \in \mathbb{R} \times [0, +\infty)$$

$$T^* := \sup\{S \geq 0 / d(x, t - \tau') \leq \rho(\tau')d(x, t), \tau' \in [0, \tau], x \in \mathbb{R}, t \in [-\tau, S]\}$$

We show by contradiction that  $T^* = +\infty$ .

By definition of  $d$ , as  $F$  is  $C_F$ -Lipschitz and  $T^* = +\infty$ :

$$\partial_t d(x, t) \geq -C_F d(x, t - \tau) \geq -C_F \rho(\tau) d(x, t)$$

Let us show that  $T^* = +\infty$  :

By contradiction, if not:

$$\forall \beta \in (0, 1), \exists \tau_\beta \in [0, \tau], \exists (x_\beta, t_\beta) \in \mathbb{R} \times (T^*, T^* + \beta) :$$

$$d(x_\beta, t_\beta - \tau_\beta) > \rho(\tau_\beta)d(x_\beta, t_\beta)$$

Preliminary result:

$$d(x, t - \tau') \leq \bar{\rho}(\tau')d(x, t) \quad \tau' \in [0, \tau], (x, t) \in \mathbb{R} \times [0, T^*]$$

with  $\bar{\rho}$  given by:

$$\bar{\rho}(\tau') = 1 + C_F \rho(\tau) \int_0^{\tau'} \rho(s) ds \quad (< \rho(\tau'))$$

Proof based on classical comparison principle for the ODE:

$$\partial_{\tau'} W = C_F \rho(\tau) \rho(\tau') W$$

**Case 1:**  $t_\beta - \tau_\beta \leq T^*$ .

$$d(x_\beta, t_\beta - \tau_\beta) = d(x_\beta, T^* - \tau'_\beta)$$

with  $\tau'_\beta := T^* - t_\beta + \tau_\beta \in [0, \tau]$

Use of preliminary result:

$$d(x_\beta, t_\beta - \tau_\beta) \leq \bar{\rho}(\tau'_\beta) d(x_\beta, T^*)$$

Moreover,  $d$  satisfies:

$$d(x, t) \geq d(x, s) - 2\|F\|_\infty(t - s) \quad (x, t) \in \mathbb{R} \times [0, +\infty), s \in [0, t]$$

Hence:

$$d(x_\beta, t_\beta - \tau_\beta) \leq \bar{\rho}(\tau'_\beta)(d(x_\beta, t_\beta) + 2\|F\|_\infty\beta)$$

Then,  $\beta < \beta_1 := \frac{\delta}{2\|F\|_\infty + 1} e^{-C_F \rho(\tau) T^*} > 0$  implies:

$$d(x_\beta, t_\beta) \geq d(x_\beta, T^*) - 2\|F\|_\infty \beta \geq \delta e^{-C_F \rho(\tau) T^*} - 2\|F\|_\infty \beta_1 = \beta_1$$

By considering  $\beta < \beta_2 := \frac{\beta_1}{2\|F\|_\infty} \inf_{[0, \tau]} (\frac{\rho}{\rho} - 1)$ , we conclude that:

$$d(x_\beta, t_\beta - \tau_\beta) \leq \rho(\tau'_\beta) d(x_\beta, t_\beta)$$

and using the fact that  $\rho$  is non decreasing and  $\tau'_\beta \leq \tau_\beta$  this contradicts

$$d(x_\beta, t_\beta - \tau_\beta) > \rho(\tau_\beta) d(x_\beta, t_\beta)$$



**Case 2:**  $t_\beta - \tau_\beta > T^*$ . This implies that  $\tau_\beta \in [0, \beta]$ . By using the fact that  $d$  is semi-Lipschitz and

$$d(x_\beta, t_\beta - \tau_\beta) > \rho(\tau_\beta)d(x_\beta, t_\beta),$$

we get:

$$(\rho(\tau_\beta) - 1)d(x_\beta, T^*) < 2\|F\|_\infty \rho(\tau_\beta)\beta$$

By using the result that came from Gronwall's lemma, we finally get:

$$0 < \delta e^{-C_F \rho(\tau) T^*} < \frac{\rho(\tau_\beta)}{\rho(\tau_\beta) - 1} 2\|F\|_\infty \beta$$

which implies  $\delta = 0$  for vanishing  $\beta$ .

## Counter-example

Here we choose  $F$  such that  $F = Id$  in  $[0, 1]$ . Let  $n_0 \in \mathbb{N}^*$  such that  $\tau > \frac{2}{n_0}$ .

Given two sets of drivers  $(X_i)_{i \in \mathbb{Z}}$  and  $(Y_i)_{i \in \mathbb{Z}}$  such that there exists  $j \in \mathbb{Z}$  such that for  $t \in [-\tau, 0]$ :

$$\begin{cases} y_j^0(t) = j - 1 + \frac{n_0}{n_0+1} e^{n_0 t} < x_j^0(t) = j \\ y_{j+1}^0(t) = j + \frac{n_0}{n_0+1} e^{n_0 t} < x_{j+1}^0(t) = y_{j+1}^0(t) + \frac{1}{n_0+1} \end{cases}$$

By direct integration, we find:

$$(Y_j - X_j)(\tau) = \frac{n_0}{n_0+1} \tau - \frac{1}{n_0+1} - \frac{1 - e^{-n_0 \tau}}{n_0+1} > 0$$

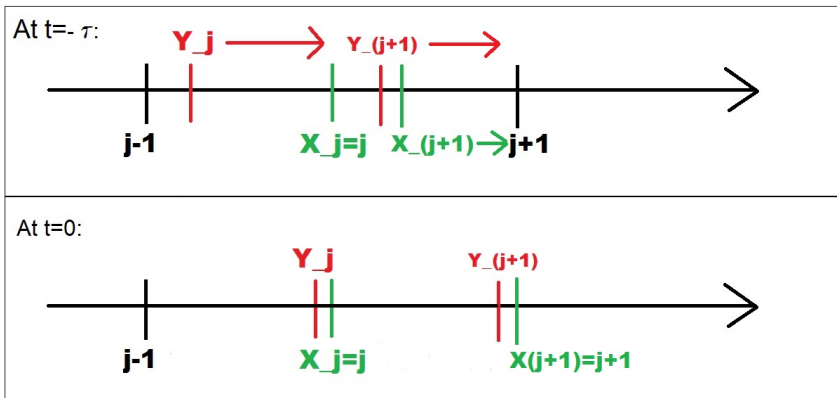


Figure : Initial dynamics for the counter-example.

# Convergence proof (sketch)

- ① Lipschitz estimates and barriers:
  - $u^\varepsilon$  is  $\|F\|_\infty$ -Lipschitz in time.
  - Strict comparison principle:  $u^\varepsilon$  is  $2L$ -Lipschitz in space.
  - Barriers:  $|u^\varepsilon(x, t) - u_0(x, t)| \leq (\|F\|_\infty + L)t$ .
  
- ② (Classical) use of relaxed semi-limits  $\bar{u}$  and  $\underline{u}$ :  
 If  $\bar{u}$  is a subsolution of the HJ equation (and  $\underline{u}$  is a supersolution)  
 then by comparison principle:

$$\bar{u} \leq u^0 \leq \underline{u}$$

$\implies$  convergence

$\bar{u}$  is a subsolution:

By contradiction, if not, there exist  $(\bar{x}, \bar{t})$ ,  $\varphi \in C_{x,t}^1$ ,  $(r, \theta, \eta) \in (0, +\infty)^3$  such that:

$$\begin{cases} \bar{u} < \varphi \text{ in } B_{2r}(\bar{x}, \bar{t}) \setminus \{(\bar{x}, \bar{t})\} \\ \bar{u}(\bar{x}, \bar{t}) = \varphi(\bar{x}, \bar{t}) \\ \bar{u} \leq \varphi - 2\eta \text{ in } B_{2r}(\bar{x}, \bar{t}) \setminus B_r(\bar{x}, \bar{t}) \end{cases}$$

and,

$$\partial_t \varphi(\bar{x}, \bar{t}) = 2\theta + F(\partial_x \varphi(\bar{x}, \bar{t}))$$

with  $B_r(y, s) := (y - r, y + r) \times (s - r, s + r)$

We define:

$$M_\varepsilon := \max_{B_{2r}(\bar{x}, \bar{t})} (u^\varepsilon - \varphi) := (u^\varepsilon - \varphi)(x_\varepsilon, t_\varepsilon)$$

For  $\varepsilon$  small enough:

$$(x_\varepsilon, t_\varepsilon) \in B_r(\bar{x}, \bar{t})$$

For  $\varphi^\varepsilon := \varphi + M_\varepsilon$ , we have (for  $\varepsilon$  small enough):

$$\begin{cases} \varphi^\varepsilon(x_\varepsilon, t_\varepsilon) = u^\varepsilon(x_\varepsilon, t_\varepsilon) \\ \partial_t \varphi^\varepsilon(x, t) \geq F\left(\frac{\varphi^\varepsilon(x+\varepsilon, t-\varepsilon\tau) - \varphi^\varepsilon(x, t-\varepsilon\tau)}{\varepsilon}\right) + \frac{\theta}{2} \text{ in } B_r(\bar{x}, \bar{t}) \end{cases}$$

Use of localised strict comparison principle:  $\varphi^\varepsilon > u^\varepsilon$  in  $B_r(\bar{x}, \bar{t})$

Contradiction with  $\varphi^\varepsilon(x_\varepsilon, t_\varepsilon) = u^\varepsilon(x_\varepsilon, t_\varepsilon)$

# Thank you for your attention